

Name: Key  
M511: Linear Algebra  
Summer 2018  
Midterm Exam: Chapters 1-3 (part I)



**Instructions.** Complete all problems below, showing enough work. Read carefully and follow all instructions. You may not use any notes or electronic devices. All you need is a pencil and your brain.

**1. True/False** [20 points] Neatly write **T** on the line if the statement is always true, and **F** otherwise [1 point each]. In the space provided below the statement, give sufficient explanation of your answer [3 point each].

T **1.a.** Every homogeneous linear system is consistent.

$\bar{x} = \bar{0}$  is always a solution.

F **1.b.** Let  $A \in \mathbb{R}^{n \times n}$ . If  $A$  is nonsingular and  $A = A^{-1}$ , then either  $A = I$  or  $A = -I$ .

e.g.  $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$   $AA = I$  so  $A^{-1} = A$ , but  $A \neq I, -I$ .

In general, any type I.

F **1.c.** Let  $A \in \mathbb{R}^{n \times n}$  and  $k \in \mathbb{R}$ . Then  $\det(k \cdot A) = k \cdot \det(A)$ .

$\det(kA) = k^n \det(A)$ .

T **1.d.** If  $\{\mathbf{x}_1, \dots, \mathbf{x}_k\}$  are vectors in a vector space  $V$  and  $\text{span}\{\mathbf{x}_1, \dots, \mathbf{x}_k\} = \text{span}\{\mathbf{x}_1, \dots, \mathbf{x}_{k-1}\}$ , then  $\{\mathbf{x}_1, \dots, \mathbf{x}_k\}$  are linearly dependent.

$\bar{x}_k = c_1 \bar{x}_1 + c_2 \bar{x}_2 + \dots + c_{k-1} \bar{x}_{k-1}$  since  $\bar{x}_k \in \text{span}\{\bar{x}_1, \dots, \bar{x}_{k-1}\}$ .

F **1.e.** Let  $A \in \mathbb{R}^{m \times n}$ . Then  $\dim(\text{Null}(A)) = \dim(\text{Null}(A^T))$ .

only true if  $m=n$ :

$$\dim(\text{row}(A)) + \dim(\text{null}(A)) = n$$

$$\text{but } \dim(\text{row}(A^T)) + \dim(\text{null}(A^T)) = m.$$

2. The matrix  $A$  is nonsingular. Compute its inverse *without* using determinants or cofactors.

$$A = \begin{pmatrix} 1 & -2 \\ -3 & 5 \end{pmatrix}$$

$$\left( \begin{array}{cc|cc} 1 & -2 & 1 & 0 \\ -3 & 5 & 0 & 1 \end{array} \right) \xrightarrow{R_2 + 3R_1 \rightarrow R_2} \left( \begin{array}{cc|cc} 1 & -2 & 1 & 0 \\ 0 & -1 & 3 & 1 \end{array} \right) \xrightarrow{-R_2 \rightarrow R_2, \text{ then } R_1 + 2R_2 \rightarrow R_1} \left( \begin{array}{cc|cc} 1 & 0 & -5 & -2 \\ 0 & 1 & -3 & -1 \end{array} \right)$$

so,  $A^{-1} = \begin{pmatrix} -5 & -2 \\ -3 & -1 \end{pmatrix}$

3. Find a basis for the null space of the matrix.

$$A = \begin{pmatrix} 1 & 1 & 1 & -1 \\ 2 & -2 & -1 & -2 \\ -1 & 3 & 2 & 1 \end{pmatrix}$$

$$\left( \begin{array}{cccc|c} 1 & 1 & 1 & -1 & 0 \\ 2 & -2 & -1 & -2 & 0 \\ -1 & 3 & 2 & 1 & 0 \end{array} \right) \rightarrow \left( \begin{array}{cccc|c} 1 & 1 & 1 & -1 & 0 \\ 0 & 4 & 3 & 0 & 0 \\ 0 & 4 & 3 & 0 & 0 \end{array} \right) \rightarrow \left( \begin{array}{cccc|c} 1 & 1 & 1 & -1 & 0 \\ 0 & 1 & 3/4 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$\begin{array}{l} 2R_1 - R_2 \rightarrow R_2 \\ R_1 + R_3 \rightarrow R_3 \end{array}$$

$$\begin{array}{l} R_2 - R_3 \rightarrow R_3, \text{ then} \\ 1/4 R_2 \rightarrow R_2 \end{array}$$

$$\begin{array}{l} \text{then,} \\ x_1 = -x_2 - x_3 + x_4 = 3/4\alpha - \alpha + \beta = -1/4\alpha + \beta \\ x_2 = -3/4 x_3 = -3/4\alpha \\ x_3 = \alpha \\ x_4 = \beta \end{array}$$

$$\text{Null}(A) = \alpha \begin{pmatrix} -1/4 \\ -3/4 \\ 1 \\ 0 \end{pmatrix} + \beta \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\text{or } \text{Null}(A) = \text{span} \left\{ \begin{pmatrix} -1/4 \\ -3/4 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}.$$

4. Consider the matrix  $A \in \mathbb{R}^{3 \times 3}$ :

$$A = \begin{pmatrix} 4 & 2 & -1 \\ -2 & 0 & 0 \\ 8 & -2 & 1 \end{pmatrix}$$

a.) Find the  $LU$  factorization of  $A$ .

b.) Use your answer to part a.) to compute the determinant of  $A$ .

a.)  $R_2 - \boxed{-\frac{1}{2}} R_1 \rightarrow R_2$   
 $R_3 - \boxed{2} R_1 \rightarrow R_3$   
 $R_3 - \boxed{-6} R_2 \rightarrow R_3$

$$\begin{pmatrix} 4 & 2 & -1 \\ 0 & 1 & -\frac{1}{2} \\ 0 & -6 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 4 & 2 & -1 \\ 0 & 1 & -\frac{1}{2} \\ 0 & 0 & 0 \end{pmatrix}$$

Thus,

$$A = \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ -\frac{1}{2} & 1 & 0 \\ 2 & -6 & 1 \end{pmatrix}}_L \underbrace{\begin{pmatrix} 4 & 2 & -1 \\ 0 & 1 & -\frac{1}{2} \\ 0 & 0 & 0 \end{pmatrix}}_U$$

b.)  $\det(A) = \det(L) \cdot \det(U) = (1 \cdot 1 \cdot 1) \cdot (4 \cdot 1 \cdot 0) = 1 \cdot 0 = 0$ .

5. Solve the linear system of equations using Cramer's Rule. Give your answers as reduced fractions. You must use Cramer's Rule to receive credit.

$$\begin{cases} 3x_1 + 5x_2 = -2 \\ 2x_1 + 4x_2 = 1 \end{cases}$$

$$A = \begin{pmatrix} 3 & 5 \\ 2 & 4 \end{pmatrix}$$

$$|A| = 12 - 10 = 2$$

$$A_1 = \begin{pmatrix} -2 & 5 \\ 1 & 4 \end{pmatrix}$$

$$|A_1| = -8 - 5 = -13$$

$$A_2 = \begin{pmatrix} 3 & -2 \\ 2 & 1 \end{pmatrix}$$

$$|A_2| = 3 + 4 = 7$$

so,  $x_1 = -\frac{13}{2}$  and  $x_2 = \frac{7}{2}$

the solution is

$$\bar{x} = \begin{pmatrix} -13/2 \\ 7/2 \end{pmatrix}$$

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6. Consider the matrix

$$A = \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix}}_{E_5} \underbrace{\begin{pmatrix} 1 & 0 \\ -2 & 1 \end{pmatrix}}_{E_4} \underbrace{\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}}_{E_3} \underbrace{\begin{pmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{pmatrix}}_{E_2} \underbrace{\begin{pmatrix} 1 & 4 \\ 0 & 1 \end{pmatrix}}_{E_1}.$$

Compute the determinant of  $A$ .

$$\det(A) = \det(E_5) \cdots \det(E_1)$$

$$= 4 \cdot 1 \cdot (-1) \cdot \left(-\frac{1}{2}\right) \cdot 1 = 2$$

7. Find the values of  $\lambda$  for which the matrix  $A \in \mathbb{R}^{3 \times 3}$  is singular.

$$A = \begin{pmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{pmatrix}$$

$$|A| = (1-\lambda)^2 - 4 = 0$$

$$(1-\lambda)^2 = 4$$

$$1-\lambda = \pm 2$$

$$\lambda - 1 = \pm 2$$

$$\lambda = 1 \pm 2$$

the values of  $\lambda$   
that make  $A$  singular are

$$\lambda = -1, 3$$

8. Solve the linear system of equations, if possible, using your favorite method.

$$\begin{cases} x_1 + 2x_2 - x_3 = 1 \\ 2x_1 - x_2 + x_3 = 3 \\ -x_1 + 2x_2 + 3x_3 = 7 \end{cases}$$

$$\left( \begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 2 & -1 & 1 & 3 \\ -1 & 2 & 3 & 7 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & -5 & 3 & 1 \\ 0 & 4 & 2 & 8 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & 1 & \frac{1}{2} & 2 \\ 0 & 0 & \frac{11}{2} & 11 \end{array} \right)$$

$R_2 - 2R_1 \rightarrow R_2$   
 $R_3 + R_1 \rightarrow R_3$

$\frac{1}{4}R_2 \leftrightarrow R_3$ , then  
 $R_3 + 5R_2 \rightarrow R_3$

$\frac{2}{11}R_3 \rightarrow R_3$

$$\rightarrow \left( \begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & 1 & \frac{1}{2} & 2 \\ 0 & 0 & 1 & 2 \end{array} \right)$$

$$x_1 = 1 - 2x_2 + x_3 = 1 - 2 + 2 = 1$$

$$x_2 = 2 - \frac{1}{2}x_3 = 2 - 1 = 1$$

$$x_3 = 2$$

Solution is

$$\bar{x} = (1, 1, 2)^T$$

9. Consider the subset of  $C^\infty(\mathbb{R})$ ,  $S = \text{span}\{e^t, e^{-t}\}$ .

a.) What is the dimension of  $S$ ? Justify your answer.

b.) Recall that  $\cosh(t) = \frac{1}{2}(e^t + e^{-t})$  and  $\sinh(t) = \frac{1}{2}(e^t - e^{-t})$ . Find the transition matrix from  $\{e^t, e^{-t}\}$  to  $\{\cosh(t), \sinh(t)\}$ .

$$a.) W(e^t, e^{-t}) = \begin{vmatrix} e^t & e^{-t} \\ e^t & -e^{-t} \end{vmatrix} = -1 - 1 = -2 \neq 0.$$

Since  $e^t, e^{-t}$  are linearly independent, then  $\dim(S) = 2$ .

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$$b.) H = \{\cosh(t), \sinh(t)\} \quad E = \{e^t, e^{-t}\}$$

$$[\cosh t] = \begin{pmatrix} 1/2 \\ 1/2 \end{pmatrix}, \quad [\sinh t] = \begin{pmatrix} 1/2 \\ -1/2 \end{pmatrix}$$

$$H = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \quad \det H = -1/2$$

$$H^{-1} = -2 \begin{pmatrix} 1/2 & 1/2 \\ -1/2 & 1/2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

so the transition matrix from  $\{e^t, e^{-t}\}$  to  $\{\cosh t, \sinh t\}$

is 
$$H^{-1} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

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10. Consider the following vectors in  $\mathbb{R}^2$ ,

$$\mathbf{u}_1 = \begin{pmatrix} 2 \\ 2 \end{pmatrix}, \quad \mathbf{u}_2 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \quad \mathbf{v}_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \quad \text{and} \quad \mathbf{v}_2 = \begin{pmatrix} -2 \\ 3 \end{pmatrix}.$$

Write  $\mathbf{x} = 4\mathbf{v}_1 - 2\mathbf{v}_2$  as a linear combination of  $\mathbf{u}_1$  and  $\mathbf{u}_2$ .

$$S: V \rightarrow U, \quad S = U^{-1}V$$

$$U = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix}, \quad U^{-1} = \frac{1}{4} \begin{pmatrix} 1 & -3 \\ -2 & 2 \end{pmatrix}, \quad V = \begin{pmatrix} 1 & -2 \\ -1 & 3 \end{pmatrix}$$

$$S = \frac{1}{4} \begin{pmatrix} 1 & -3 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} 1 & -2 \\ -1 & 3 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 4 & -11 \\ -4 & 10 \end{pmatrix}$$

$$[\bar{\mathbf{x}}]_U = S [\bar{\mathbf{v}}]_V = \frac{1}{4} \begin{pmatrix} 4 & -11 \\ -4 & 10 \end{pmatrix} \begin{pmatrix} 4 \\ -2 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 38 \\ -36 \end{pmatrix}_U$$

$$\text{so } \boxed{\bar{\mathbf{x}} = \frac{-19}{2} \bar{u}_1 + 9 \bar{u}_2}$$