

Math 511: Linear Algebra

Sy2018

Midterm Review Guide - Brief Solutions

$$1. \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 2 & -1 & 1 & 3 \\ -1 & 2 & 3 & 7 \end{array} \right) \xrightarrow{\text{R}_2 - 2\text{R}_1 \rightarrow \text{R}_2} \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & -5 & 3 & 1 \\ -1 & 2 & 3 & 7 \end{array} \right) \xrightarrow{\frac{1}{4}\text{R}_2 \leftrightarrow \text{R}_3, \text{ then } \text{R}_3 + 5\text{R}_2 \rightarrow \text{R}_3} \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & 1 & \frac{1}{2} & 2 \\ 0 & 0 & \frac{11}{2} & 11 \end{array} \right)$$

$\text{R}_2 - 2\text{R}_1 \rightarrow \text{R}_2$
 $\text{R}_3 + \text{R}_1 \rightarrow \text{R}_1$
 $\frac{1}{4}\text{R}_2 \leftrightarrow \text{R}_3$, then
 $\text{R}_3 + 5\text{R}_2 \rightarrow \text{R}_3$
 $\frac{2}{11}\text{R}_3 \rightarrow \text{R}_3$

$$\xrightarrow{} \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & 1 & \frac{1}{2} & 2 \\ 0 & 0 & 1 & 2 \end{array} \right) \quad \begin{aligned} x_1 &= 1 - 2x_2 + x_3 = 1 - 2 + 2 = 1 \\ x_2 &= 2 - \frac{1}{2}x_3 = 2 - 1 = 1 \\ x_3 &= 2 \end{aligned} \quad \text{solution is} \quad \hat{x} = (1, 1, 2)^T$$

$$2. \left(\begin{array}{ccc|c} 1 & 5 & -2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \quad \begin{aligned} x_1 &= 3 - 5x_2 + 2x_3 \\ x_2 &= \alpha \in \mathbb{R} \\ x_3 &= \beta \in \mathbb{R} \\ x_4 &= 0 \end{aligned} \quad \tilde{x} = \begin{pmatrix} 3 \\ 0 \\ 0 \\ 0 \end{pmatrix} + \alpha \begin{pmatrix} -5 \\ 1 \\ 0 \\ 0 \end{pmatrix} + \beta \begin{pmatrix} 2 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \alpha, \beta \in \mathbb{R}.$$

$$3. AB = \begin{pmatrix} 3 & 5 & 1 \\ -2 & 0 & 2 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 1 & 3 \\ 4 & 1 \end{pmatrix} = \begin{pmatrix} 6+5+4 & 3+15+1 \\ -4+0+8 & -2+0+2 \end{pmatrix} = \begin{pmatrix} 15 & 19 \\ 4 & 0 \end{pmatrix}$$

$$4. R = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}, \quad R^T = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

$$RR^T = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} \cos^2 \theta + \sin^2 \theta & \cos \theta \sin \theta - \sin \theta \cos \theta \\ \cos \theta \sin \theta - \sin \theta \cos \theta & \cos^2 \theta + \sin^2 \theta \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Hence $R^T = R^{-1}$.

$$5. A = \begin{pmatrix} -2 & 4 \\ 6 & 8 \end{pmatrix} \rightarrow \begin{pmatrix} -2 & 4 \\ 0 & 20 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

1. $R_2 + 3R_1 \rightarrow R_2$
 2. $\frac{1}{20}R_2 \rightarrow R_2$
 3. $-\frac{1}{2}R_1 \rightarrow R_1$

$$\text{So, } A^{-1} = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 20 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 3 & 1 \end{pmatrix}$$

$$6. \left(\begin{array}{ccc|cc} 2 & 5 & 1 & 1 & 0 \\ 1 & 3 & 0 & 0 & 0 \\ 2 & 5 & 0 & 0 & 1 \end{array} \right) \xrightarrow{\text{R}_1 \leftrightarrow \text{R}_2, \text{ then}} \left(\begin{array}{ccc|cc} 1 & 3 & 0 & 0 & 1 \\ 0 & -1 & 1 & 1 & 0 \\ 2 & 5 & 0 & 0 & 1 \end{array} \right) \xrightarrow{\text{R}_2 \leftrightarrow \text{R}_3, \text{ then}} \left(\begin{array}{ccc|cc} 1 & 3 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 1 & 0 \end{array} \right) \xrightarrow{\text{R}_1 - 3\text{R}_2 \rightarrow \text{R}_1} \left(\begin{array}{ccc|cc} 1 & 0 & 0 & 0 & -5 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 1 & 0 \end{array} \right) \quad \text{So,}$$

$\text{R}_1 \leftrightarrow \text{R}_2, \text{ then}$
 $\text{R}_2 - 2\text{R}_1 \rightarrow \text{R}_2$
 $\text{R}_3 - 2\text{R}_1 \rightarrow \text{R}_3$
 $\text{R}_2 \leftrightarrow \text{R}_3, \text{ then}$
 $\text{R}_3 + \text{R}_2 \rightarrow \text{R}_3$
 $\text{R}_1 - 3\text{R}_2 \rightarrow \text{R}_1$

$$A^{-1} = \begin{pmatrix} 0 & -5 & 3 \\ 0 & 2 & -1 \\ 1 & 0 & -1 \end{pmatrix}$$

$$7. \begin{pmatrix} A^{-1} \\ I \end{pmatrix} (A \ I) = \begin{pmatrix} A^{-1}A & A^{-1} \\ A & I \end{pmatrix} = \begin{pmatrix} I & A^{-1} \\ A & I \end{pmatrix}$$

$$8. A = \begin{pmatrix} -2 & 1 & 2 \\ 4 & 1 & -2 \\ -6 & -3 & 4 \end{pmatrix} \rightarrow \begin{pmatrix} -2 & 1 & 2 \\ 0 & 3 & 2 \\ 0 & -6 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} -2 & 1 & 2 \\ 0 & 3 & 2 \\ 0 & 0 & 2 \end{pmatrix} = U$$

$R_2 - 2R_1 \rightarrow R_2$

$R_3 - 3R_1 \rightarrow R_3$

$R_3 - 2R_2 \rightarrow R_3$

$$L = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -2 & 1 \end{pmatrix}$$

$$\text{so, } A = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -2 & 1 \end{pmatrix} \begin{pmatrix} -2 & 1 & 2 \\ 0 & 3 & 2 \\ 0 & 0 & 2 \end{pmatrix}$$

$$9. a) |A| = 2 \begin{vmatrix} 4 & 2 \\ -1 & 3 \end{vmatrix} - 3 \begin{vmatrix} -2 & 2 \\ 1 & 3 \end{vmatrix} + 5 \begin{vmatrix} -2 & 4 \\ 1 & -1 \end{vmatrix} = 2(12+2) - 3(-6-2) + 5(2-4) = 28 + 24 - 10 = 42.$$

b.) Inverse via cofactor method:

$$\begin{aligned} M_{11} &= \begin{pmatrix} 4 & 2 \\ -1 & 3 \end{pmatrix} & M_{12} &= \begin{pmatrix} -2 & 2 \\ 1 & 3 \end{pmatrix} & M_{13} &= \begin{pmatrix} -2 & 4 \\ 1 & -1 \end{pmatrix} \\ M_{21} &= \begin{pmatrix} 3 & 5 \\ -1 & 3 \end{pmatrix} & M_{22} &= \begin{pmatrix} 2 & 5 \\ 1 & 3 \end{pmatrix} & M_{23} &= \begin{pmatrix} 2 & 3 \\ 1 & -1 \end{pmatrix} \\ M_{31} &= \begin{pmatrix} 3 & 5 \\ 4 & 2 \end{pmatrix} & M_{32} &= \begin{pmatrix} 2 & 5 \\ -2 & 2 \end{pmatrix} & M_{33} &= \begin{pmatrix} 2 & 3 \\ -2 & 4 \end{pmatrix} \end{aligned} \left\{ \begin{array}{l} C_A = \begin{pmatrix} 14 & 8 & -2 \\ -14 & 1 & 5 \\ -14 & -14 & 14 \end{pmatrix}, \text{ so} \\ A^{-1} = \frac{1}{42} \begin{pmatrix} 14 & -14 & -14 \\ 8 & 1 & -14 \\ -2 & 5 & 14 \end{pmatrix} \end{array} \right.$$

$$10. A = \begin{pmatrix} 5 & 7 \\ -8 & 3 \end{pmatrix} \quad |A| = 15 + 56 = 71$$

$$A_1 = \begin{pmatrix} 1 & 7 \\ -1 & 3 \end{pmatrix} \quad |A_1| = 3 + 7 = 10 \quad \text{so} \quad \bar{x} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 10/71 \\ 3/71 \end{pmatrix}$$

$$A_2 = \begin{pmatrix} 5 & 1 \\ -8 & -1 \end{pmatrix} \quad |A_2| = -5 + 8 = 3$$

$$11. 1 = \det(I) = \det(Q^T Q) = \det(Q^T Q) = \det(Q^T) \cdot \det(Q) = \det Q \cdot \det Q = (\det Q)^2 \quad \text{so} \quad \det Q = \pm 1$$

$$12. A = \begin{pmatrix} 1-\lambda & \sqrt{3} \\ \sqrt{3} & -1-\lambda \end{pmatrix}, \quad |A| = (1-\lambda)(-1-\lambda) - \sqrt{3}^2 = \lambda^2 - 1 - 3 = \lambda^2 - 4 = (\lambda-2)(\lambda+2)$$

so A is singular iff $\lambda = \pm 2$.

$$13. \det(A) = \det(LU) = \det(L)\det(U) = \det U = 2 \cdot 1 \cdot (-2) \cdot 5 = -20.$$

$$14. \bar{x} = 4\bar{u}_1 - 2\bar{u}_2 = \begin{pmatrix} 4 \\ -2 \end{pmatrix}_U. \quad \text{The transition matrix from } U \text{ to } V \text{ is } S = V^{-1}U.$$

$$U = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix}, \quad V = \begin{pmatrix} 1 & -2 \\ -1 & 3 \end{pmatrix}, \quad V^{-1} = \frac{1}{7} \begin{pmatrix} 3 & 2 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 3 & 2 \\ 1 & 1 \end{pmatrix}$$

$$\text{so, } S = V^{-1}U = \begin{pmatrix} 3 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 10 & 11 \\ 4 & 4 \end{pmatrix} \quad \text{and} \quad [x]_V = S[x]_U = \begin{pmatrix} 10 & 11 \\ 4 & 4 \end{pmatrix} \begin{pmatrix} 4 \\ 2 \end{pmatrix}_U = \begin{pmatrix} 18 \\ 8 \end{pmatrix}_V$$

$$\boxed{|\bar{x}| = 18\bar{v}_1 + 8\bar{v}_2}$$

$$15. A = \begin{pmatrix} -3 & 1 & 3 & 4 \\ 1 & 2 & -1 & -2 \\ 6 & -3 & -5 & -7 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & -1 & -2 \\ 0 & 7 & 0 & -2 \\ 0 & -15 & 1 & 5 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & -1 & -2 \\ 0 & 1 & 0 & -2/7 \\ 0 & 0 & 1 & 5/7 \end{pmatrix}$$

$R_1 \leftrightarrow R_2$, then

$\frac{1}{7}R_2 \rightarrow R_2$, then

$R_2 + 3R_3 \rightarrow R_2$

$R_3 - 6R_1 \rightarrow R_3$

$$x_1 = -\frac{4}{7}t - \frac{5}{7}t + 2t = \frac{5}{7}t$$

$$x_2 = \frac{2}{7}t$$

$$x_3 = -\frac{5}{7}t$$

$$x_4 = t$$

$$\text{so, } \text{Row}(A) = \text{Span} \{ (1, 2, -1, -2), (0, 1, 0, -2/7), (0, 0, 1, 5/7) \}$$

$$\text{Col}(A) = \text{Span} \{ \begin{pmatrix} -3 \\ 1 \\ 6 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix}, \begin{pmatrix} 3 \\ -1 \\ -5 \end{pmatrix} \} \subseteq \mathbb{R}^3 \quad \text{so any basis is acceptable.}$$

$$\text{Null}(A) = \text{Span} \{ (5, 2, -5, 7)^T \}$$

16. a.) PREF: $\begin{pmatrix} 1 & 0 & 1 & 3 & 0 \\ 0 & 1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$ b.) $\text{Col}(A) = \text{span}\{\bar{a}_1, \bar{a}_2, \bar{a}_3\} = \mathbb{R}^3$.
c.) $x_5=0, x_4=\beta, x_3=2, x_2=2+\beta, x_1=-2-3\beta \Rightarrow \text{Null}(A) = \text{span}\{(-1, 1, 1, 0, 0), (-3, 1, 0, 1, 0)\}$.

17. All 10 axioms must be checked: $\bar{x}=x, \bar{y}=y, \bar{z}=z$ in $(\mathbb{R}, \oplus, \otimes)$ and α, β in $(\mathbb{R}, +, \cdot)$

A1. $\alpha \otimes \bar{x} = \alpha x + (1-\alpha)b \in \mathbb{R}$ ✓

A2. $\bar{x} \oplus \bar{y} = x+y-b \in \mathbb{R}$ ✓

A3. $\bar{x} \oplus \bar{y} = x+y-b = y+x-b = \bar{y} \oplus \bar{x}$ ✓

A4. $\bar{x} \oplus (\bar{y} \oplus \bar{z}) = x+(y+z-b)-b = x+y+z-b-b = (x+y-b)+z-b = (\bar{x} \oplus \bar{y}) \oplus \bar{z}$ ✓

A5. $\bar{x} = \bar{x} + \bar{0} = x + ? - b = x$ implies $? = b$,
So the zero vector in this space is $\boxed{\bar{0} = b}$ ✓

A6. $\bar{x} \oplus (-\bar{x}) = \bar{0} \Rightarrow x + (-x) - b = b \Rightarrow \boxed{-\bar{x} = -x + 2b}$ This exists for each $\bar{x} \in (\mathbb{R}, \oplus, \otimes)$ ✓

A7. $\alpha \otimes (\bar{x} \oplus \bar{y}) = \alpha(\bar{x} \oplus \bar{y}) + (1-\alpha)b = \alpha(x+y-b) + (1-\alpha)b = \alpha x + \alpha y - \alpha b + b - \alpha b$
 $= \alpha x + b - \alpha b + \cancel{\alpha y} + \cancel{b} - \cancel{\alpha b} - b = \alpha x + (1-\alpha)b + \cancel{\alpha y} + (1-\alpha)b - b$
 $= (\alpha \otimes \bar{x}) \oplus (\alpha \otimes \bar{y})$ ✓

A8. $(\alpha+\beta) \otimes \bar{x} = (\alpha+\beta)x + (1-(\alpha+\beta))b = \alpha x + \beta x + b - \alpha b - \beta b$
 $= \alpha x + b - \alpha b + \cancel{\beta x} + \cancel{b} - \cancel{\beta b} = \alpha x + (1-\alpha)b + \beta x + (1-\beta)b - b$
 $= (\alpha \otimes \bar{x}) \oplus (\beta \otimes \bar{x})$ ✓

A9. $(\alpha\beta) \otimes \bar{x} = \alpha\beta x + (1-\alpha\beta)b = \alpha(\beta x) + b - \alpha(\beta b) = \alpha(\beta x + b - \beta b) - \cancel{\alpha b} + b = \alpha(\beta x + (1-\beta)b) + (1-\alpha)b$
 $= \alpha \otimes (\beta \otimes \bar{x})$

One can (and you should) show in a similar fashion that this is equivalent to $\beta \otimes (\alpha \otimes \bar{x})$.

A10. $1 \otimes \bar{x} = 1x + (1-1)b = x = \bar{x}$ ✓